# **OpenRoads Designer User Manual**



**U.S. Department** of Transportation Federal Highway<br>Administration

# **Chapter 21**

# TERRAIN MODEL ANALYSIS TOOLS



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# **Chapter 21 Terrain Model Analysis Tools**

This chapter describes the tools used to analyze Terrain Models and also contains a workflow for Sight Visibility (SSD and PSD) analysis. All tools described in this chapter are found under the **Terrain** tab and in the **Analysis** group.



*NOTE:* Most Terrain Model Analysis tools are NOT compatible with Corridors and Linear Templates. However, a Corridor or Linear Template can be quickly converted into a Terrain Model using the *Create Terrain Model from Design Meshes* tool. See *22A.1 Create Terrain Model from Design Meshes tool*.

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#### **21A – POINTS TOOLS**

<span id="page-3-0"></span>Points tools are used to analyze point locations on a Terrain Model. These tools create a label element that measure the elevation, slope, and other parameters along a Terrain Model.

Points tools are found in the Ribbon in the following location:

#### **OpenRoads Modeling** workflow → **Terrain** tab → **Analysis** group → **Points** drop-down



#### <span id="page-3-1"></span>**21A.1 Analyze Between Points tool**

The *Analyze Between Points* tool creates a label that measures slope between two-point locations on a Terrain Model. This tool can be operated from either the *2D Design Model* D or *3D Design Model* D

*NOTE:* This tool is NOT directly compatible with Corridors and Linear Templates. The Corridor or Linear Template must be converted into a Terrain Model for use with this tool. Use the *Create Terrain Model from Design Meshes* tool to convert Corridors and Linear Templates into a Terrain Model. See *22A.1 Create Terrain Model from Design Meshes*.



*TIP:* When placing the slope label, elevation and geometry information relating to the two-point locations is shown in the *Dialogue Box* and *Quick Information Box*.





#### <span id="page-5-0"></span>**21A.2 Analyze Point tool**

With this tool, a 3D element type is selected and a point location is analyzed for northing, easting, elevation and other parameters.



As shown below, many 3D element types that are compatible with this tool, including Corridors and Linear Templates. The analysis information shown in the *Dialogue Box* depends on the type of element selected.

#### **Selecting a Terrain Model:**



**Selecting an Alignment, 3D Linear Element, or Corridor Linework:**



#### **Selecting a Mesh element (Corridors, Linear Templates, and Surface Templates):**



**TIP:** After selecting an element, hover the mouse cursor (ensure that Snaps are turned ON) over a different Linear Element. Information relating to the Linear Element will display in the *Dialogue Box*.

As shown below, a Corridor Mesh (Pavement Layer 1) element is selected. Next, the mouse cursor is hovered over a Linear Element (Culvert). The Culvert element contains an *Active Profile*.

The *Dialogue Box* shows comparison information between the Mesh and Linear Element. **Z On Snap**  represents the **Linear Element (Culvert)** at the mouse cursor location. The **Z Difference** represents the height difference between the **Linear Element Profile** and **Corridor Mesh** elevations.



#### <span id="page-7-0"></span>**21A.3 Analyze Elevation tool**

This tool creates a report that compares the elevation between a Terrain Model and 3D Linear Element (i.e., an Alignment).



The Terrain Model and 3D Linear Element elevations are compared at every vertex location along the 3D Linear Element.



This tool allows a **Tolerance** to be specified and analyzed. The Tolerance represents the elevation difference between the Terrain Model and 3D Linear Element. If the elevation difference is less than the Tolerance, then "Within" is shown in the results table. If the elevation difference exceeds the Tolerance, then "Outside" is shown.

*NOTE:* This tool requires the 3D Linear Element to be selected from the 3D Design Model **b**.

*TIP:* Multiple 3D Linear Elements can be selected for comparison.

As a practical demonstration of this tool, the Edge of Pavement (3D Linear Element) and Existing Ground Terrain Model are selected for elevation comparison. The Edge of Pavement line is generated from the Corridor.





#### <span id="page-9-0"></span>**21A.4 Inverse Points tool**

The *Inverse Point* tool measures and annotates 2D/3D elements or between point locations. Measurements can be made either in the 2D Design Model <sup>Q</sup>1 or 3D Design Model **R**1.



This tool contains many different methods (Input Types) for measuring. Graphical demonstrations of each Input Type is shown on the next page.



The remaining CHECK BOXES for the *Inverse Points* tool are explained below:









#### **21B – CALCULATE AREA TOOL**

<span id="page-13-0"></span>This tool calculates the **Planar Area** and **Slope Area** of a Terrain Model.

**Planar Area:** Represents the plan or footprint area of the Terrain Model. The Planar Area is the 2 dimensional area of the Terrain Model.

**Slope Area:** Represents the 3-dimensional area of the Terrain Model. The Slope Area accounts for tilted and sloped areas in the Terrain Model.



*TIP:* Optionally, a Fence can be placed before operation of this tool. If the **Use Fence** box is CHECKED, then ONLY the Terrain Model area within the Fence limits is calculated.

#### **21C – VOLUMES TOOLS**

<span id="page-14-0"></span>These tools are used to analyze the volume of a Terrain Model relative to a different Terrain Model or to a plane elevation.

Volume tools are found in the Ribbon in the following location:

#### **OpenRoads Modeling** workflow → **Terrain** tab → **Analysis** group → **Volumes** drop-down



*NOTE:* Detailed workflows for calculating Cut and Fill volumes from Corridors, Linear Templates, and Surface Templates are shown in *Chapter 20 – Quantities*. Additionally, the *Create Cut Fill Volumes* tool is described in *20B.2 Create Cut Fill Volumes tool – Workflow*.

# <span id="page-15-0"></span>**21C.1 Analyze Volume tool**

This tool calculates the cut/fill volumes between two Terrain Models OR between a Terrain Model and a flat plane set at a specified elevation.



*NOTE:* If analyzing between an Existing and Proposed Terrain Model:

- Select the **Existing Terrain Model** as the "**From Terrain Model**" (as shown in step 3).
- Select the **Proposed Terrain Model** as the "**To Terrain Model**" (as shown in step 4).

*TIP:* Create a Proposed Terrain Model from Corridors, Linear Templates, and Surface Templates using the *Create Terrain Model From Design Meshes* tool. To create a Sub-Grade Terrain Model, select **Bottom** for the **Select Side of Closed Mesh** option. See *22A.1 Create Terrain Model from Design Meshes tool*.

*TIP:* Optionally, a boundary element can be drawn and selected for the volume analysis (as shown in step 7). If selected, then the resulting cut/fill volumes are ONLY calculated within the limits of the boundary. The boundary element can be drawn in the *2D Design Model* using MicroStation Tools (i.e., *Place SmartLine* tool).









#### **21D – HYDRAULIC TOOLS**

<span id="page-17-0"></span>The tools describe in this section are used to analyze the surface hydraulics of a Terrain Model. Hydraulic Tools are found in the Ribbon in the following location:

**OpenRoads Modeling** workflow → **Terrain** tab → **Analysis** group → **Hydraulics** drop-down



*NOTE:* Hydraulic Tools are for simple Terrain Model analysis. **Drainage and Utilities** tools are used to perform complex hydraulic analysis and layout/modeling for drainage systems. See *Chapter 25 – Drainage Analysis (Drainage and Utilities tools)*.

#### <span id="page-18-0"></span>**21D.1 Analyze Pond tool**

The *Analyze Pond* tool analyzes a Terrain Model for depressions and low areas (ponding). Depressions in the Terrain Model are automatically delineated and can be selected to reveal more information relating to the Volume, Depth, Ponding Elevation, and Ponding Area.

*NOTE:* This tool has difficulty delineating ponds in the Existing Ground Terrain Model because existing ponds typically have many minor depressions on the bottom surface. With this tool, a depression is ONLY analyzed up to the FIRST spillover elevation. This causes each minor depression to be analyzed, instead of the real-world pond volume.

Shown below is a cross section view of an existing pond. This tool ONLY analyzes the depression shown on the left, because it spills over to the minor depression shown on the right.



Shown below are the results of *Analyze Pond* tool when ran on an Existing Ground Terrain Model. The delineated Ponding Area are shown in red. Each minor depression in the Terrain Model is delineated. On the left-side of this graphic is a real-world pond that is NOT fully delineated because it contains minor depressions on the bottom.



*Analyze Ponds* **tool workflow:** As shown in the following workflow, this tool is most useful for analyzing ponds that have a smooth, uniform bottom; such as a proposed detention basin.



**General Settings:** The values shown in the General drop-down apply to the last pond area selected.



**Filter Settings:** Optionally, a filter can be applied to display ONLY ponds that exceed a specified Area or Depth. After a filter has been set, push the **Apply** button to reprocess the ponding results and apply the filter.



**Feature Settings:** If a Feature Definition and Name is set, then a 3D Linear Element is created around the perimeter of a pond area.



# <span id="page-21-0"></span>**21D.2 Analyze Trace Slope tool**

This tool analyzes flow lines or lines of constant slope on a Terrain Model. *TIP\*:* A **Feature Definition**  must be set in the *Dialogue Box* for this tool to draw the slope lines.

There are two **Trace Methods** for operating this tool: **Maximum Trace Slope** and **Constance Slope Trace.**

**Maximum Trace Slope:** With this method, a point-location is specified on a Terrain Model and a line is drawn along the path of maximum slope. The resulting line can be interpreted as the flow path of a water when dropped on the point-location.



The Slope Line terminates when it reaches a depression point in the Terrain Model. In a depression point, there is no direction where a downward slope can be achieved.

The **Minimum Depth** setting is used to pass over depressions that are shallower than the specified depth. For example, in the graphic above, the **Minimum Depth** is set to 0.3000 and cause the Slope Line to terminate at the depression in the Terrain Model. In the graphic below, the **Minimum Depth** is set to 1.0000 and the Slope Line passes over the depression point.



#### **Maximum Slope Trace** – **Workflow:**



*NOTE:* The resulting Slope Line is a 3D Linear Element and is placed in the *3D Design Model* . To delete the Slope Line, locate it in the *3D Design Model* .

**Constant Trace Method:** This method creates a Slope Line that follows a constant slope path along the Terrain Model. In the *Dialogue Box*, the **Slope** setting controls the constant slope value.



# <span id="page-24-0"></span>**21D.3 Create HEC-RAS Data tool**

This tool analyzes a Terrain Model to create a HEC-RAS geometry file (.geo). This tool requires the following elements to create the HEC-RAS data:



- **Terrain Model:** The Terrain Model is analyzed to determine elevations for the Cross Section Lines.
- **Cross Sections Lines:** Must be oriented/drawn from right bank to left bank when looking upstream. All Cross Section Lines must be within the boundary of the Existing Ground Terrain Model. Commonly, Stream Cross Sections are surveyed and placed on the "E\_HYD\_Stream\_X-Section" Level. However, Stream Cross Sections may be manually drawn or traced using a MicroStation Element (i.e., a Smart Line).
- **Stream Alignment or Reach:** Must be oriented/drawn from downstream to upstream. Commonly, the Stream Alignment is surveyed and placed on the "E\_HYD\_Stream\_Profile" Level. However, the Stream Alignment should be an ORD Element (i.e., an Alignment). Using an ORD Element is advantageous because the ORD Element can be stationed and assigned a (Reach) Name. Stationing and Name will carry over to the HEC-RAS data. *BEST PRACTICE:* Manually draw or trace the Stream Alignment using ORD Elements. The Stream Alignment should be a continuous ORD Element.
- **Left/Right Bank Line:** Must be oriented/drawn from downstream to upstream. Commonly, Bank Lines are surveyed and placed on the "E\_GEO\_Top\_of\_Bank" Level. A Bank Line element must be continuous along the entire reach. Bank Lines can be manually drawn or traced using a MicroStation Element. *WARNING:* Typically, the Edge of Water Linework should NOT be chosen as the Bank Lines. The Edge of Water represents the water level at the time of the survey, which may be lower than the bank.
- **Left/Right Over Bank Line:** Must be oriented/drawn from downstream to upstream. In HEC-RAS, the Over Bank Lines determine the **Downstream Reach Lengths** for the **LOB** and **ROB**. The Over Bank Lines correspond with Reach Lengths for over bank flow. Typically, the Over Bank Lines are NOT surveyed and must be drawn manually using MicroStation Elements. *TIP:* The Bank Line can be selected as the Over Bank Line. In other words, a single element can serve as both the Bank Line and Over Bank Line.

**IMPORTANT:** The direction of the elements must be oriented in the appropriate direction for correct importation into HEC-RAS. The Stream Cross Sections Lines must be drawn from right bank to left bank,

if looking upstream. All other elements (i.e., Banks, Over Banks, and the Stream Alignment) must be drawn from downstream to upstream.



#### **Create HEC-RAS Data – Workflow:**



In steps 5-7, the **Bank**, **Over Bank**, and **Cross Section Lines** are drawn or setup using MicroStation Elements. If these lines have been surveyed, then use the *Copy* tool to bring the referenced survey elements into the current ORD File as a MicroStation Element. There are two checks that must be performed before the copied MicroStation Elements can be used with the *Create HEC-RAS Data* tool:

• Ensure the lines are continuous. For example, a Bank Line must be a single, continuous element. If there is a gap in a line, then use *Place Smart Line* tool to draw a line between the gap. Use the *Create Complex Chain* tool to combine multiple lines into a single MicroStation Element. See *6H.2 Create Complex Chain tool*.



• Ensure the Lines are oriented in the appropriate direction. Use the "*Change Direction*" Key-In to check the direction of a Line and reverse it if necessary. The "*Change Direction*" Key-In is demonstrated in *6I.5 Flip the Direction of a Line Style*.













After step 16, all information is analyzed and packaged into a HEC-RAS Geometry File (.geo). Specify a location for the HEC-RAS Geometry File.



**Import the Data into HEC-RAS:** With the Geometric Data window opened, the **Import Geometry Data**  tool is used to import the data gathered from the ORD Software. *IMPORTANT:* Use the **GIS Format**  option to import the data. *WARNING:* Do NOT use the HEC-RAS Format.





#### **21E – REPORTING TOOLS**

<span id="page-31-0"></span>Reporting tools are used to locate conflicting break lines or points within a Terrain Model.

Reporting tools are found in the Ribbon in the following location:

#### **OpenRoads Modeling** workflow → **Terrain** tab → **Analysis** group → **Reporting** drop-down



*NOTE:* Reporting tools have very limited usages for design and drafting purposes. These tools are generally used by surveyors when creating and analyzing the Existing Ground Terrain Models for errors.

# <span id="page-32-0"></span>**21E.1 Report Crossing Features tool**

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This tool analyzes a Terrain Model for intersecting break lines and voids. For example, a Terrain Model may contain two break lines which cross. It is possible for each break line to be set a different elevation at the intersection point. This tool locates the crossing features and provides options for reconciling the difference between conflicting elevations to automatically fix the Terrain Model.

*NOTE:* This tool has limited applicability for design work. Instead, this tool is most useful for surveyors when creating and analyzing the Existing Ground Terrain Model for break line discrepancies.

In the example shown below, the **Edge of Road** and **Edge of Approach** break lines are both used in the Existing Ground Terrain Model. The *Report Crossing Features* tool creates a report that shows the elevation of both break lines at the intersection point.



After step 4, the *Report Crossing Features* report is created and all Break Line Intersection Points are listed. As shown in the report below, there is an Elevation Difference of 0.041 feet at the intersection point of the **Edge of Road** and **Edge of Approach** break lines.



By Right-Clicking on an Intersection Point, the elevation discrepancy can be automatically fixed and the Terrain Model will be adjusted.





# <span id="page-34-0"></span>**21E.2 Report Conflicting Points tool**

This tool analyzes a Terrain Model for two or more Points placed at in the same horizontal position, but at different elevations.

For example, a Terrain Model used to create the surface of an Approach requires a closed Boundary element to be created. When creating the Profile of the Boundary element, the start point of the Profile should be placed at the same elevation as the end point.

However, if the start and end point are errantly placed at differing elevations, the conflicting elevations will be located and listed by the *Report Conflicting Points* tool. Also, the differing elevation points can be automatically reconciled by this tool.





After step 4, the *Report Conflicting Points* report is created and all conflicting points in the Terrain Model are listed. As shown in the report below, there is an Elevation Difference of 0.152 feet at the Start/End Point of the Boundary element.



By Right-Clicking on a Point, the elevation discrepancy can be automatically fixed.





#### **21F – AQUAPLANING TOOL**

<span id="page-37-0"></span>The *Aquaplaning* tool analyzes the Finished Ground Terrain Model to create a report that measures film depth along the length of the road for a specified rainfall intensity.

*NOTE:* The FLH WorkSpace does NOT support Feature Definitions for use of this tool. This tool is NOT used in FLH projects.



**TIP:** Analyzing the Corridor or Finished Ground Terrain Model with Thematic Displays can be used to identify flat areas that may result in ponding or aquaplanning. For more information on Thematic Displays, see *21H – Use Thematic Display Styles to Analyze Slopes*.

#### **21G – SIGHT VISIBILITY TOOL**

<span id="page-38-0"></span>The *Sight Visibility* tool generates sight lines and a report that analyzes the Stopping Sight Distance (SSD) or Passing Sight Distance (PSD) at station intervals along the mainline alignment.



In practice, this tool has two main usages:

- Determine areas with inadequate Stopping Sight Distance (SSD). For example, if an object was placed on the roadway, this tool analyzes if a vehicle has adequate Stopping Sight Distance to come to a stop before reaching the object.
- Analyze Passing Sight Distance (PSD) to determine passing zones. Once passing zones are determined, appropriate pavement markings can be drawn in for the permeant traffic control plan. For example, for two lane highways, this tool can be used to determine placement of broken yellow centerline markings that designate passing zones.

# <span id="page-39-0"></span>**21G.1 Capabilities and Limitations of the** *Sight Visibility* **tool**

At every station interval, this tool draws a 3-dimensional sight line from the eye location of the motorist to the object location, which is placed further down the mainline alignment. The distance from the eye location to the object is set by the SSD or PSD distance required for the motorist operating speed. The SSD or PSD distance is measured along the Alignment and represents the path of the vehicle.



In operation of this tool, the Proposed Finished Grade Terrain Model or a Corridor is selected. Sight Line failure is determined if the Finished Grade Terrain Model or Corridor obstructs the sight line from the eye location to the object. Acceptable sight lines are shown in green. Failed sight lines are shown in red.

As shown below, the sight line is shown in red (failure) because the proposed crest vertical curve interrupts the sightline between the eye and object.



**Sight Lines that extend past the Finished Grade Terrain Model or Corridor:** Optionally, this tool allows the Existing Ground Terrain Model to be selected to further analyze sight lines that extend past the selected Finished Grade Terrain Model/Corridor. In areas where the Existing Ground Terrain Model and Finished Grade Terrain Model/Corridor overlap, the Existing Ground Terrain Model is ignored.

**Limitation – Accounting for Other Vertical Obstructions (i.e., trees and buildings):** As mentioned above, this tool analyzes Terrain Models and/or Corridors for sight line obstructions due to grade changes. Trees, buildings, and other vertical obstructions are NOT analyzed because they are NOT a part of the Existing Ground Terrain Model.

Accounting for vertical obstructions can be done manually by examining the resulting sight lines from the *2D Design Model* (plan view). *BEST PRACTICE:* After using this tool, scroll down the alignment and search for sight lines that extend past vertical obstructions (i.e., trees, buildings, clearing limits) or the right-of-way.

*TIP:* Turn on the *Background Map* aerial to assist in identifying vertical obstructions. See *3D – Setup a New ORD File*.



For example, in the graphic above, all sight-lines are deemed acceptable by the *Sight Visibility* tool because the Terrain Models/Corridor grade changes do NOT obstruct the sight-line. However, there is an area that would be obstructed by the surveyed Tree Line.

*TIP:* When scrolling down the alignment, isolate Levels that correspond with vertical obstructions, such as the tree line (E\_VEG\_Tree\_Line), buildings (E\_PLM\_BLDG\_Building), and clearing limits (P\_RDW\_Clearing\_Limts). Also, it is commonly undesirable to have sight lines extend past the existing or proposed right-of-way and property lines (E\_RW\_Right\_of\_Way\_Lines, P\_RW\_Right\_of\_Way).

*TIP:* In step 29 of the *21G.2 Sight Visibility – Workflow*, the start station for analysis is specified. Before accepting the start station, a sight line is dynamically drawn. Move the dynamic sight line down the length of the alignment to quickly identify locations that are obstructed by surveyed or proposed linework. Vertical obstructions can be automatically analyzed by creating a 3D model of the obstruction and adding it to the Existing Ground Terrain Model. However, modeling each obstruction area can be very time consuming and will slightly alter the triangulation of the Existing Ground Terrain Model when added.



In summation, the process for modeling an obstruction area is as follows:

*NOTE:* For this process, a new ORD File should be created. The Survey ORD File must be *merged*  (imported) into the new ORD File to make modifications to the Existing Ground Terrain Model. Specifically, the Survey ORD File must be *merged* into the *3D Design Model* to import the Existing Ground Terrain Model.



Open the *Profile Model*  $\boxplus$  for an Obstruction Area element.

Using the *Copy* tool, copy the profile for the Existing Ground Profile and place it in the same location. *Activate* the copied Profile.

*WARNING:* Do NOT directly a*ctivate* the Existing Ground Profile. *Activate* the copy. If the Existing Ground Profile is directly *activated*, then the Obstruction Area element will be rejected when adding it to the Existing Ground Terrain Model.

Return to the *2D Design Model* .

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Using the *Move Parallel* tool, create an offset copy of the Obstruction Area element. Place the Offset element 0.5 feet within the Obstruction Area element.

Open the *Profile Model*  $\boxplus$  for the offset copy.

Using the *Copy* tool, copy the Existing Ground Profile and place it directly above the original location using AccuDraw. Place the copy 15-20 feet above original location. *Activate* the copied Profile.



Enter the *3D Design Model* .

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*NOTE:* After *activating* the Profiles for both the Obstruction Area element and Offset element, corresponding *3D Linear Elements* are shown in the *3D Design Model* .

Add the *3D Linear Elements* to the Existing Ground Terrain Model using the *Add Features* tool.

*IMPORTANT:* Add the Obstruction Area element as a Break Line.

*IMPORTANT:* Add the Offset element as a Break Void.

*NOTE:* When using the *Add Features* tool, the elements to be added must be selected from the *3D Design Model* .



**Limitation – Accounting for Grade in SSD Calculations:** A variable in the Stopping Sight Distance (SSD) formula is the current grade (G) that the vehicle is traveling on.

*Greenbook Equation (3-3):* 

$$
d_B = \frac{V^2}{30[\frac{a}{32.2} \pm G]}
$$

Where:

 $d_R$  = Breaking Distance on grade (ft)

 $V =$  Design speed (mph)

 $a =$  deceleration (ft/s<sup>2</sup>)

 $G =$  Current Grade  $(% )$ 

Unfortunately, the ORD software suffers from a known bug, that prevents the Instantaneous Grade and Average Grade information to be collected, which means the calculated Stopping Sight Distance does NOT account for Average Grade.



As a workaround, FLH has a Microsoft Excel spread sheet template that calculate Average Grade based on the **Eye Level** and **Object Level** elevations. The values generated in the **Sight Visibility Results Table**  are copied into FLH spread sheets to automatically calculate SSD values that account for grade. Exporting the Sight Visibility Results table into the FLH spread sheet template is discussed in *21G.3 Import Results into Microsoft Excel Template*.

**TIP:** Another workaround for addressing the average grade bug is to locate steepest grade on the project from the Alignment Profile. Use Table 3-2 from the AASHTO Greenbook to determine the SSD distance for the steepest grade. In step 10 of the *21G.2 Sight Visibility - Workflow*, a custom Distance (SSD) value can be specified. Enter the SSD distance for the steepest grade during this step. The resulting analysis will be more conservative because the worst-case situation is analyzed.

**Limitation – Maximum Sight Distance is NOT Calculated:** Knowing the Maximum Sight Distance that a motorist can see is beneficial in areas of marginal SSD or PSD. This tool does NOT provide additional analysis or extend a sight line after SSD or PSD is achieved.

For example, if the SSD is 200 feet (speed = 30 mph), analysis is ceased when determined that 200 feet of Sight Distance is achievable. In this case, the motorist has a Maximum Sight Distance of 220 feet (As shown in the results table below), which is marginal compared to the SSD of 200 feet. This marginal area may be of interest to the designer.



As a workaround, the operating speed or SSD (Distance) variable can be increased when using the *Sight Visibility* tool. In the example shown above, failure is invoked by increasing the speed from 30 mph to 35 mph, which changes the target SSD value from 200 feet to 250 feet.

In the Sight Visibility Results Table, failed sight lines (shown with red rows) can be analyzed in the **Sight Distance Achieved** column. The value shown in this column is the Maximum Sight Distance at the station.



*BEST PRACTICE:* When using the *Sight Visibility* tool, set the Speed to 5-10 mph greater than the actual operating speed of the road. For failed sight-lines, compare the **Sight Distance Achieved** with the actual SSD of the road. This practice allows areas of marginal SSD to be identified.

**Limitation – Only 1 Direction of Traffic is Analyzed per Use of the Tool:** This tool can analyze sight lines either forwards or backwards along the alignment. However, it CANNOT analyze both directions at the same time.

To analyze sight lines **forwards** along the alignment, the start station must be less than the end station.

To analyze sight lines **backwards** along the alignment, set the start station to a value grater than the end station.



*TIP:* When analyzing **backwards** along the alignment, set the start station to a round station (i.e., 12+50). In the resulting report, the station intervals will be set to round values (i.e., 12+50, 12+00, 11+50, etc…).

WARNING: If the start station is set to an irregular station (i.e., 12+56.23), then then resulting report will list station intervals relative to the start station (i.e., 12+56.26, 12+06.56, 11+56.26, etc...).

# <span id="page-47-0"></span>**21G.2 Sight Visibility – Workflow**

In this workflow, the *Sight Visibility* tool is used to generate sight lines and a results report.

When using this tool either the Alignment or Corridor can be selected (which is shown in step 26). If the Alignment is selected, then a **Design Surface** (i.e., the Proposed Finished Grade Terrain Model) must also be selected. The Design Surface is used to calculate the Eye Level and Object Level and analyze for obstructions due to grade change. Creating a Finished Grade Terrain Model from a Corridor is shown in *22A.1 Create Terrain Model from Design Meshes tool*.

**Selecting the Corridor vs Alignment/Design Surface:** If the Corridor is selected, then only the top surface of the Corridor is analyzed for sight line obstructions. If an Alignment/Design Surface is selected, then a Design Surface can be created using a combination of Corridors, Linear Templates, and Surface Templates. All Corridors, Linear Templates, and Surface Templates included in the Design Surface are analyzed for sight line obstructions.

*NOTE:* As stated above, either the Corridor or the Alignment/Design Surface can be selected. Regardless of the selection, the Existing Ground Terrain Model can also be selected. In areas beyond the Corridor or Alignment/Design Surface, the Existing Ground Terrain Model is analyzed for sight line obstructions.







This tool requires the User to follow *Prompts* (shown around the mouse cursor) and configure the *Dialogue Box* for correct operation.

**Dialogue Box Configuration:** Steps 6-11 explain how to configure the **Parameters** options in the *Dialogue Box*.





Steps 12-17 explain how to configure the **Eye Position** and **Object Position** options in the *Dialogue Box:*







 $19<sup>7</sup>$ Assign the *Sight Visibility* run a descriptive **Name**. For example: "SSD Eastbound 40 MPH".



The remainder of the steps in this procedure follow the *Floating Prompts*. *NOTE:* Steps 20-25 correspond with steps 6-11, which where set in the *Dialogue Box*. The parameters and values set in the *Dialogue Box*  will display in the *Floating Prompt* box.













*Prompt: Data Point to Accept Design –* Left-Click in the *View* window to place the sight line graphics and view the results table.

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*TIP:* There are two methods for deleting a previously-created run of the *Sight Visibility* tool:

- Select the sight line elements from the **3D Design Model b** and delete it. **NOTE:** Sight-lines CANNOT be deleted by selecting the sight lines in the *2D Design Model .*
- Locate the *Sight Visibility* run in the Explorer<sup>ed</sup>. Previously-created *Sight Visibility* runs are located under the **OpenRoads Model** drop-down and in the **Sight Visibility Sections** drop-down.

**TIP:** Retrieve a Sight Visibility Results Table for a previously-created run from the Explorer <sup>eq</sup>: Right-Click on the run and select the *Sight Visibility Results* option.



#### **TIP:** Export the Sight Visibility Results Table to Microsoft Excel:





As shown in the graphic report above, the Average Grade and Instant Grade columns are zeroed out. To account for grade in the SSD/PSD calculations, the results table must be imported into the FLH spread sheet template, which is shown the next section.

# <span id="page-57-0"></span>**21G.3 Import Results into the Microsoft Excel Template**

The resulting tables from the SSD or PSD analysis must be copied into FLH spreadsheet template to account for grade in the calculations and create a report. The FLH SSD and PSD spread sheet templates are located at:

<https://highways.dot.gov/federal-lands/design/forms/sight-distance>

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*NOTE:* Generation of the Microsoft Excel results table from ORD is shown on the previous page. Both the ORD results and FLH template spread sheets must be opened for this procedure.



In the Microsoft Excel results table, select all cells by pushing the Triangle button located in the upper-left corner. Right-Click and select **Copy**.

In the FLH spread sheet template, select either the "Alg Upstation" or "Alg Downstation" tab. The selected tab depends on which direction along the alignment the Microsoft Excel Results table was generated from.

Select the Triangle button located in the upper-left corner. Right-Click and select **Paste**.



#### **Repeat Steps 1-3 for the opposing direction along the alignment. Ensure that results generated from ORD are copied into both the "Alg Upstation" and "Alg Downstation" tabs.**

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In the FLH spread sheet template, select either the "Upstation Analyzed" or "Downstation Analyzed" tab

Expand the **Design Speed** drop-down located in cell E1. Select the appropriate design speed.

Repeat steps 4-5 for the opposing direction along the alignment. Ensure the Design Speed has been selected in both the "Upstation Analyzed" and Downstation Analyzed" tabs.



After the design speed has been selected, select the "**Upstation Analyzed Filter**" and "**Downstation**  Analyzed Filter" tabs to review the results. Results shown in the "Level Roadway Only (Tool Output)" table are generated directly from ORD. Results shown in the "Accounting for Grade" calculate the SSD with the effect of grade accounted for. These results use the ORD generated eye level and object level elevations to calculate an approximate average grade.



#### **21H – USE THEMATIC DISPLAY STYLES TO ANALYZE SLOPES**

<span id="page-60-0"></span>Using the "Thematic:Slope" Display Style, slopes along a Corridor, Linear Template, Terrain Model can be analyzed. The "Thematic:Slope" Display Style can be used to locate flat pavement areas where a drainage/ponding issue may form or to review slopes along a model to ensure ADA/ABA compliance.

The "Thematic:Slope" Display Style color-grades the surface of the Corridor, Linear Template, or Terrain Model. A legend is shown in the upper-right corner of the *View* window that identifies the approximate slope of each colored area.

*NOTE:* Thematic Display Styles are ONLY available in the *3D Design Model* . This analysis must be performed from the *3D Design Model* .



The "Thematic: Slope" Display Style must be edited in the Display Style Editor for effective use. By default, this Display Style uses degree units in the legend and color grading. The Display Style should be edited to show percent units, instead of the default degree units.

When editing the Display Style, a slope range should be specified. The default slope range (which is 0%) to 100%) is too broad, which causes areas of shallow slope are displayed as completely flat. In the graphic above, the slope range is edited to ONLY show slopes from 0.00%-2.00%, which means slopes greater than 2.00% are NOT shown and color-graded.

Setting the range from 0.00%-2.00% is useful for locating areas where ponding or drainage may be an issue. The narrow slope range is necessary to depict small changes of slope in relatively flat areas. If the slope range was set from 0.00%-10.00%, then areas of slope between 0% and 1.9% are shown as completely flat (0.00%).

**BEST PRACTICE:** Set and adjust the slope range to isolate areas of interest. Engineering judgement may be required in setting the slope range for the particular analysis. A recommended slope range for identifying drainage and ponding issues is 0% - 2%. A recommended slope range for assessing ADA/ABA compliance is 2% - 10%.

#### **Workflow for Setting and Editing the "Thematic:Slope" Display Style:**







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