# **OpenRoads Designer User Manual**



U.S. Department of Transportation Federal Highway Administration

# Chapter 21

# TERRAIN MODEL ANALYSIS TOOLS



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# Chapter 21 Terrain Model Analysis Tools

This chapter describes the tools used to analyze Terrain Models and also contains a workflow for Sight Visibility (SSD and PSD) analysis. All tools described in this chapter are found under the **Terrain** tab and in the **Analysis** group.



**NOTE:** Most Terrain Model Analysis tools are NOT compatible with Corridors and Linear Templates. However, a Corridor or Linear Template can be quickly converted into a Terrain Model using the *Create Terrain Model from Design Meshes* tool. See 22A.1 Create Terrain Model from Design Meshes tool.

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#### **21A - POINTS TOOLS**

Points tools are used to analyze point locations on a Terrain Model. These tools create a label element that measure the elevation, slope, and other parameters along a Terrain Model.

Points tools are found in the Ribbon in the following location:

#### **OpenRoads Modeling** workflow $\rightarrow$ **Terrain** tab $\rightarrow$ **Analysis** group $\rightarrow$ **Points** drop-down



#### 21A.1 Analyze Between Points tool

The *Analyze Between Points* tool creates a label that measures slope between two-point locations on a Terrain Model. This tool can be operated from either the *2D Design Model* **2** or *3D Design Model* **5**.

**NOTE:** This tool is NOT directly compatible with Corridors and Linear Templates. The Corridor or Linear Template must be converted into a Terrain Model for use with this tool. Use the *Create Terrain Model from Design Meshes* tool to convert Corridors and Linear Templates into a Terrain Model. See 22A.1 Create Terrain Model from Design Meshes.



**TIP:** When placing the slope label, elevation and geometry information relating to the two-point locations is shown in the *Dialogue Box* and *Quick Information Box*.





# 21A.2 Analyze Point tool

With this tool, a 3D element type is selected and a point location is analyzed for northing, easting, elevation and other parameters.



As shown below, many 3D element types that are compatible with this tool, including Corridors and Linear Templates. The analysis information shown in the *Dialogue Box* depends on the type of element selected.

#### Selecting a Terrain Model:



Selecting an Alignment, 3D Linear Element, or Corridor Linework:



#### Selecting a Mesh element (Corridors, Linear Templates, and Surface Templates):



**TIP:** After selecting an element, hover the mouse cursor (ensure that Snaps are turned ON) over a different Linear Element. Information relating to the Linear Element will display in the *Dialogue Box*.

As shown below, a Corridor Mesh (Pavement Layer 1) element is selected. Next, the mouse cursor is hovered over a Linear Element (Culvert). The Culvert element contains an *Active Profile*.

The *Dialogue Box* shows comparison information between the Mesh and Linear Element. **Z On Snap** represents the **Linear Element (Culvert)** at the mouse cursor location. The **Z Difference** represents the height difference between the **Linear Element Profile** and **Corridor Mesh** elevations.



### 21A.3 Analyze Elevation tool

This tool creates a report that compares the elevation between a Terrain Model and 3D Linear Element (i.e., an Alignment).



The Terrain Model and 3D Linear Element elevations are compared at every vertex location along the 3D Linear Element.



This tool allows a **Tolerance** to be specified and analyzed. The Tolerance represents the elevation difference between the Terrain Model and 3D Linear Element. If the elevation difference is less than the Tolerance, then "Within" is shown in the results table. If the elevation difference exceeds the Tolerance, then "Outside" is shown.

**NOTE:** This tool requires the 3D Linear Element to be selected from the 3D Design Model

**TIP:** Multiple 3D Linear Elements can be selected for comparison.

As a practical demonstration of this tool, the Edge of Pavement (3D Linear Element) and Existing Ground Terrain Model are selected for elevation comparison. The Edge of Pavement line is generated from the Corridor.



1	From the Ribbon, select the <i>Analyze Elevation</i> tool: [ <i>OpenRoads Modeling</i> $\rightarrow$ <i>Terrain</i> $\rightarrow$ <i>Analysis</i> $\rightarrow$ <i>Points</i> ].
2	<i>Prompt: Select Terrain or Reset to use Active Terrain</i> – Select the Existing Ground Terrain Model or right-click (reset) to select whatever Terrain Model is <i>active</i> .
3	<i>Prompt: Locate First Element</i> – Locate the 3D Linear Element to be compared with the Terrain Model. In this case, the Edge of Pavement line from the Corridor is selected.
4	<i>Prompt: Locate Next Element</i> – Either select another 3D Linear Element for comparison or right- click (reset) to advance to the next prompt.
5	<i>Prompt: Enter Tolerance Value</i> – Enter a Tolerance value for analysis in the resulting report.
	After this step, a report will be created.

## 21A.4 Inverse Points tool

The *Inverse Point* tool measures and annotates 2D/3D elements or between point locations. Measurements can be made either in the 2D Design Model  $\Omega$  or 3D Design Model  $\overline{\Box}$ .



This tool contains many different methods (Input Types) for measuring. Graphical demonstrations of each Input Type is shown on the next page.

Inputs Types and Modes										
Input Type:	Description:	Mode:								
Linear	Measures the linear distance,	direction, and ele	evations between two-point locations.							
Arc	The geometry of an arc is defined by clicking in several point locations. Geometry information for the arc is measured and reported.	Radius Point	First, a start point on the perimeter of the arc is specified. Next, the center point of the arc is specified. Last, the end point on the perimeter of the arc is specified.							
	<b>NOTE:</b> Use the <b>By Element</b> type to measure a previously-created arc element.	Point on Curve	First, a start point on the perimeter of the arc is specified. Next, the end point of the arc is specified. Last, a point along the length of the arc is specified.							
Radial	Used to make multiple Linea common start point. All Linea	<b>r</b> measurements. ar measurements	Each measurement begins from a are radial to the start point.							
Perpendicular	Used to make a Linear measurement that begins perpendicularly from an	By Element	First, an element is selected. Next, a point location is specified. The linear distance measured is perpendicular from the point to the element.							
	element.	Between Points	Measures the perpendicular linear distance between two points.							
By Element	An element is selected and m Lines, Arcs, Complex Chains,	easured. The follo and Complex Eler	owing element types are compatible: nents (Alignments and Profiles).							

The remaining CHECK BOXES for the *Inverse Points* tool are explained below:

	Inverse Points Dialogue Box Settings						
Setting:	Description:						
	If CHECKED, then elevation of the selected element or point location is analyzed.						
Report 3D	<b>NOTE:</b> This option is ONLY relevant when measuring in the <i>3D Design Model</i> <b>•</b> . When using this tool in the <i>2D Design Model</i> <b>2</b> , the Profile elevation of the selected element is NOT reported.						
	If CHECKED, then an annotation with all the measurement information is shown.						
Annotate	<b>NOTE:</b> If the <b>Persist</b> box is UNCHECKED, then the annotation will disappear after operation of this tool.						
Persist	This box is only relevant if the <b>Annotate</b> box is CHECKED. If CHECKED, then an Annotation element is created and will persist after the operation of this tool.						
Send Output	If CHECKED, then a report with all measurement information is created.						
Use Point Name	Optionally, a previously-created Survey Point or ORD Point can be used in the measurement. If the name of the Point is known, then the name can be typed here for use in the measurement.						







#### 21B - CALCULATE AREA TOOL

This tool calculates the **Planar Area** and **Slope Area** of a Terrain Model.

**Planar Area:** Represents the plan or footprint area of the Terrain Model. The Planar Area is the 2dimensional area of the Terrain Model.

**Slope Area:** Represents the 3-dimensional area of the Terrain Model. The Slope Area accounts for tilted and sloped areas in the Terrain Model.



**TIP:** Optionally, a Fence can be placed before operation of this tool. If the **Use Fence** box is CHECKED, then ONLY the Terrain Model area within the Fence limits is calculated.

#### **21C – VOLUMES TOOLS**

These tools are used to analyze the volume of a Terrain Model relative to a different Terrain Model or to a plane elevation.

Volume tools are found in the Ribbon in the following location:

#### **OpenRoads Modeling** workflow $\rightarrow$ **Terrain** tab $\rightarrow$ **Analysis** group $\rightarrow$ **Volumes** drop-down

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**NOTE:** Detailed workflows for calculating Cut and Fill volumes from Corridors, Linear Templates, and Surface Templates are shown in <u>Chapter 20 – Quantities</u>. Additionally, the <u>Create Cut Fill Volumes</u> tool is described in <u>20B.2 Create Cut Fill Volumes tool – Workflow</u>.

# 21C.1 Analyze Volume tool

This tool calculates the cut/fill volumes between two Terrain Models OR between a Terrain Model and a flat plane set at a specified elevation.



**NOTE:** If analyzing between an Existing and Proposed Terrain Model:

- Select the Existing Terrain Model as the "From Terrain Model" (as shown in step 3).
- Select the Proposed Terrain Model as the "To Terrain Model" (as shown in step 4).

**TIP:** Create a Proposed Terrain Model from Corridors, Linear Templates, and Surface Templates using the *Create Terrain Model From Design Meshes* tool. To create a Sub-Grade Terrain Model, select **Bottom** for the **Select Side of Closed Mesh** option. See <u>22A.1 Create Terrain Model from Design Meshes tool</u>.

**TIP:** Optionally, a boundary element can be drawn and selected for the volume analysis (as shown in step 7). If selected, then the resulting cut/fill volumes are ONLY calculated within the limits of the boundary. The boundary element can be drawn in the 2D Design Model **2** using MicroStation Tools (i.e., *Place SmartLine* tool).



From the Ribbon, select the *Analyze Volumes* tool: [*OpenRoads Modeling*  $\rightarrow$  *Terrain*  $\rightarrow$  *Analysis*  $\rightarrow$  *Volumes*].

2	<i>Prompt: Enter Volume Method</i> – Select either "Terrain Model to Terrain Model Volume" or "Terrain Model to Plane". If "Terrain Model to Plane" is selected, then a Plane elevation is specified in the next step.
3	Prompt: Locate From Terrain Model – Select the Existing Ground Terrain Model.
4	Prompt Locate To Terrain Model – Select the Proposed Terrain Model.
5	<i>Prompt: Enter Cut Factor</i> – If desired, enter a multiplier value for the resulting Cut volume. The Cut Factor typically corresponds with the "shrink factor".
6	<i>Prompt: Enter Fill Factor -</i> If desired, enter a multiplier value for the resulting Fill volume. The Fill Factor typically corresponds with the "swell factor"
7	<i>Prompt: Boundary Reset For None</i> – Right-Click (reset) to NOT use a boundary element. The boundary of the "To Terrain Model" (step 4) is used for the analysis.
	If desired, manually draw and select a Boundary element. The analysis will ONLY calculate the Terrain Model volume within the limits of the Boundary element.
8	<i>Prompt: Save Volume –</i> If YES is selected, then an annotation element that shows the volume analysis is created.
	If NO is selected, then the volume analysis values can be found in the <i>Dialogue Box</i> .



#### **21D - HYDRAULIC TOOLS**

The tools describe in this section are used to analyze the surface hydraulics of a Terrain Model. Hydraulic Tools are found in the Ribbon in the following location:

**OpenRoads Modeling** workflow  $\rightarrow$  **Terrain** tab  $\rightarrow$  **Analysis** group  $\rightarrow$  **Hydraulics** drop-down

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**NOTE:** Hydraulic Tools are for simple Terrain Model analysis. **Drainage and Utilities** tools are used to perform complex hydraulic analysis and layout/modeling for drainage systems. See <u>Chapter 25</u> – Drainage Analysis (Drainage and Utilities tools).

## 21D.1 Analyze Pond tool

The *Analyze Pond* tool analyzes a Terrain Model for depressions and low areas (ponding). Depressions in the Terrain Model are automatically delineated and can be selected to reveal more information relating to the Volume, Depth, Ponding Elevation, and Ponding Area.

**NOTE:** This tool has difficulty delineating ponds in the Existing Ground Terrain Model because existing ponds typically have many minor depressions on the bottom surface. With this tool, a depression is ONLY analyzed up to the FIRST spillover elevation. This causes each minor depression to be analyzed, instead of the real-world pond volume.

Shown below is a cross section view of an existing pond. This tool ONLY analyzes the depression shown on the left, because it spills over to the minor depression shown on the right.



Shown below are the results of *Analyze Pond* tool when ran on an Existing Ground Terrain Model. The delineated Ponding Area are shown in red. Each minor depression in the Terrain Model is delineated. On the left-side of this graphic is a real-world pond that is NOT fully delineated because it contains minor depressions on the bottom.



**Analyze Ponds tool workflow:** As shown in the following workflow, this tool is most useful for analyzing ponds that have a smooth, uniform bottom; such as a proposed detention basin.



**General Settings:** The values shown in the General drop-down apply to the last pond area selected.

	Analyze Ponds – General Settings
Setting:	Description:
Volume	Displays the volume of the selected pond in cubic feet.
Depth	Displays the maximum depth of the selected pond in feet.
Elevation	Displays the ponding elevation (water surface) of the selected pond.
Area	Displays the top water surface area of the selected pond.
Selection	This method allows for manual selection of Template Points for inclusion the report. This method is demonstrated in the following workflow.

**Filter Settings:** Optionally, a filter can be applied to display ONLY ponds that exceed a specified Area or Depth. After a filter has been set, push the **Apply** button to reprocess the ponding results and apply the filter.

Analyze Ponds - Filter Settings							
Setting:	Description:						
No Pond Filtering	All ponding areas are shown. No ponding areas are filtered out.						
Filter Ponds By Area	Only ponding areas that exceed the <b>Minimum Area</b> value are shown.						
Filter Ponds By Depth	Only ponding areas that exceed the <b>Minimum Depth</b> value are shown.						
Minimum Area/Depth	This value works in conjunction with the <b>Filter Bonds By Area/Depth</b> settings. <b>NOTE: Minimum Area</b> is in square feet units. <b>Minimum Depth</b> is in feet units.						
Apply	Push this button to apply the filter.						

**Feature Settings:** If a Feature Definition and Name is set, then a 3D Linear Element is created around the perimeter of a pond area.

Analyze Ponds - Feature Settings							
Setting:	Description:						
Feature Definition	Sets the Feature Definition for the resulting 3D Linear Element.						
Name	Sets the Name for the resulting 3D Linear Element.						

# 21D.2 Analyze Trace Slope tool

This tool analyzes flow lines or lines of constant slope on a Terrain Model. **TIP\*:** A **Feature Definition** must be set in the *Dialogue Box* for this tool to draw the slope lines.

There are two **Trace Methods** for operating this tool: **Maximum Trace Slope** and **Constance Slope Trace.** 

**Maximum Trace Slope:** With this method, a point-location is specified on a Terrain Model and a line is drawn along the path of maximum slope. The resulting line can be interpreted as the flow path of a water when dropped on the point-location.



The Slope Line terminates when it reaches a depression point in the Terrain Model. In a depression point, there is no direction where a downward slope can be achieved.

The **Minimum Depth** setting is used to pass over depressions that are shallower than the specified depth. For example, in the graphic above, the **Minimum Depth** is set to 0.3000 and cause the Slope Line to terminate at the depression in the Terrain Model. In the graphic below, the **Minimum Depth** is set to 1.0000 and the Slope Line passes over the depression point.



#### Maximum Slope Trace – Workflow:

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3	In the	e Dialogue	Box,	set <b>Fe</b>	ature Defi	nition a	and Nar	<b>ne</b> for	the S	lope Li	ne ele	emen	t to be	e drawn.	
4	In the	e Dialogue	Box,	set the	e Trace Me	<b>thod</b> to	Maxin	num Sl	оре	Trace.					
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**NOTE:** The resulting Slope Line is a 3D Linear Element and is placed in the *3D Design Model* **•**. To delete the Slope Line, locate it in the *3D Design Model* **•**.

**Constant Trace Method:** This method creates a Slope Line that follows a constant slope path along the Terrain Model. In the *Dialogue Box*, the **Slope** setting controls the constant slope value.



# 21D.3 Create HEC-RAS Data tool

This tool analyzes a Terrain Model to create a HEC-RAS geometry file (.geo). This tool requires the following elements to create the HEC-RAS data:



- **Terrain Model:** The Terrain Model is analyzed to determine elevations for the Cross Section Lines.
- Cross Sections Lines: Must be oriented/drawn from right bank to left bank when looking upstream. All Cross Section Lines must be within the boundary of the Existing Ground Terrain Model. Commonly, Stream Cross Sections are surveyed and placed on the "E\_HYD\_Stream\_X-Section" Level. However, Stream Cross Sections may be manually drawn or traced using a MicroStation Element (i.e., a Smart Line).
- Stream Alignment or Reach: Must be oriented/drawn from downstream to upstream. Commonly, the Stream Alignment is surveyed and placed on the "E\_HYD\_Stream\_Profile" Level. However, the Stream Alignment should be an ORD Element (i.e., an Alignment). Using an ORD Element is advantageous because the ORD Element can be stationed and assigned a (Reach) Name. Stationing and Name will carry over to the HEC-RAS data. *BEST PRACTICE:* Manually draw or trace the Stream Alignment using ORD Elements. The Stream Alignment should be a continuous ORD Element.
- Left/Right Bank Line: Must be oriented/drawn from downstream to upstream. Commonly, Bank Lines are surveyed and placed on the "E\_GEO\_Top\_of\_Bank" Level. A Bank Line element must be continuous along the entire reach. Bank Lines can be manually drawn or traced using a MicroStation Element. WARNING: Typically, the Edge of Water Linework should NOT be chosen as the Bank Lines. The Edge of Water represents the water level at the time of the survey, which may be lower than the bank.
- Left/Right Over Bank Line: Must be oriented/drawn from downstream to upstream. In HEC-RAS, the Over Bank Lines determine the Downstream Reach Lengths for the LOB and ROB. The Over Bank Lines correspond with Reach Lengths for over bank flow. Typically, the Over Bank Lines are NOT surveyed and must be drawn manually using MicroStation Elements. *TIP:* The Bank Line can be selected as the Over Bank Line. In other words, a single element can serve as both the Bank Line and Over Bank Line.

**IMPORTANT:** The direction of the elements must be oriented in the appropriate direction for correct importation into HEC-RAS. The Stream Cross Sections Lines must be drawn from right bank to left bank,

if looking upstream. All other elements (i.e., Banks, Over Banks, and the Stream Alignment) must be drawn from downstream to upstream.



#### **Create HEC-RAS Data – Workflow:**

1	Create a new ORD File using a 2D Seed File. See 3B - Create a New ORD File.
2	In the new ORD File, reference in the Survey ORD File.
3	Activate the Existing Ground Terrain Model.
	Draw or trace the <b>Stream Alignment (Reach)</b> using ORD Element Tools.
	Draw the Alignment from downstream to upstream. Use the Line Between Points tool to draw a series of connected, line segments. See 7D.1.a.i Lines Between Points.
	Combine the line segments into a single, continuous Alignment using the Complex By Element tool. When using the Complex By Element, ensure the resulting Alignment direction is oriented from downstream to upstream (as indicated by the purple arrow). See 7D.2.a Complex By Elements tool.
4	<b>TIP:</b> Assign the Stream Alignment to the "Baseline" Feature Definition. In the Properties <b>(</b> ) box, assign the Alignment a Name.
	<b>TIP:</b> Use the Start Station tool to set the start station value for the Stream Alignment. See <b>7E.4.a Start Station</b> .
	<b>TIP:</b> Use the Annotate Element tool to create alignment/station annotations for the Stream Alignment. See <b>15D.2 Alignment Annotations – Workflow.</b>
	<b>ALTERNATE WORKFLOW:</b> If a Stream Alignment was surveyed (i.e., a survey element placed on the "E_HYD_Stream_Profile" Level), then use the Copy tool to bring the survey element in to the current ORD File. The referenced survey element is converted to a Line String (MicroStation Element) when copied in to the current ORD File. Use the Complex By Element tool to convert the MicroStation Element into an ORD Element. The ORD Element can be named and stationed.

In steps 5-7, the **Bank**, **Over Bank**, and **Cross Section Lines** are drawn or setup using MicroStation Elements. If these lines have been surveyed, then use the *Copy* tool to bring the referenced survey elements into the current ORD File as a MicroStation Element. There are two checks that must be performed before the copied MicroStation Elements can be used with the *Create HEC-RAS Data* tool:

Ensure the lines are continuous. For example, a Bank Line must be a single, continuous element. If
there is a gap in a line, then use *Place Smart Line* tool to draw a line between the gap. Use the *Create Complex Chain* tool to combine multiple lines into a single MicroStation Element. See 6H.2 Create
Complex Chain tool.



Ensure the Lines are oriented in the appropriate direction. Use the "*Change Direction*" Key-In to check the direction of a Line and reverse it if necessary. The "*Change Direction*" Key-In is demonstrated in **61.5 Flip the Direction of a Line Style**.

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8	From the Ribbon, select the <i>Create HEC-RAS Data</i> tool: [ <i>OpenRoads Modeling</i> $\rightarrow$ <i>Terrain</i> $\rightarrow$ <i>Analysis</i> $\rightarrow$ <i>Hydraulic</i> ].
9	<i>Prompt: Locate First Section Line</i> – Select a <b>Cross Section Line</b> . <i>NOTE:</i> Cross Section Lines can be selected in any order. They do NOT have to be selected from downstream to upstream.
10	Prompt: Locate Next Section Line – Reset to Complete – Select the remaining <b>Cross Section</b> <b>Lines</b> . After selecting the last Cross Section Line, right-click (reset) to advance to the next Prompt.
11	<i>Prompt: Select Terrain or Reset to Use Active Terrain</i> – Select the Existing Ground Terrain Model. Alternatively, if the Existing Ground Terrain Model is <i>active</i> , then right-click (reset) to select it.





After step 16, all information is analyzed and packaged into a HEC-RAS Geometry File (.geo). Specify a location for the HEC-RAS Geometry File.



**Import the Data into HEC-RAS:** With the Geometric Data window opened, the **Import Geometry Data** tool is used to import the data gathered from the ORD Software. *IMPORTANT:* Use the **GIS Format** option to import the data. *WARNING:* Do NOT use the HEC-RAS Format.

📻 HEC-RAS 5.0.7		– 🗆 X	
File Edit Run View Options GIS Tools He	۹b		
	<u>aza - Filta E</u>	🔲 🖆 oss 🛛 🚺	
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Import Geometry Data >	GIS Format		
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Hrea	UNET Geometry Format		
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	Mike 11 Cross Sections		
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#### **21E – REPORTING TOOLS**

Reporting tools are used to locate conflicting break lines or points within a Terrain Model.

Reporting tools are found in the Ribbon in the following location:

#### **OpenRoads Modeling** workflow $\rightarrow$ **Terrain** tab $\rightarrow$ **Analysis** group $\rightarrow$ **Reporting** drop-down



**NOTE:** Reporting tools have very limited usages for design and drafting purposes. These tools are generally used by surveyors when creating and analyzing the Existing Ground Terrain Models for errors.

#### 21E.1 **Report Crossing Features tool**

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This tool analyzes a Terrain Model for intersecting break lines and voids. For example, a Terrain Model may contain two break lines which cross. It is possible for each break line to be set a different elevation at the intersection point. This tool locates the crossing features and provides options for reconciling the difference between conflicting elevations to automatically fix the Terrain Model.

**NOTE:** This tool has limited applicability for design work. Instead, this tool is most useful for surveyors when creating and analyzing the Existing Ground Terrain Model for break line discrepancies.

In the example shown below, the **Edge of Road** and **Edge of Approach** break lines are both used in the Existing Ground Terrain Model. The Report Crossing Features tool creates a report that shows the elevation of both break lines at the intersection point.



After step 4, the *Report Crossing Features* report is created and all Break Line Intersection Points are listed. As shown in the report below, there is an Elevation Difference of 0.041 feet at the intersection point of the **Edge of Road** and **Edge of Approach** break lines.

	Terrain Crossing Feature Types • P Z	es Report oom To 🙆 Report All 🧕 I	n View 😂 Export 🖉 Draw	<b>g Features</b> Selected Radius: 5	- Report	×	
/	Intersection Point 2263336.142, -3123948.744	Elevation On Feature 1 1411.643	Elevation On Feature 2 1411.684	Elevation Difference	Feature Type 1 Breakline	Feature Type 2 Breakline	
	<b>TIP:</b> To locate a select (highli <b>Intersection I</b> push the <b>Zoom</b>	a crossing, ght) an <b>Point</b> and <b>To</b> button.	Elevation Di	fference Break Lines	TIP: W is	hen an <b>Intersection</b> selected (highlighted)	Point
			at the <b>Intersec</b>	tion Point.	Fea	ture 2 is shown in B	lue

By Right-Clicking on an Intersection Point, the elevation discrepancy can be automatically fixed and the Terrain Model will be adjusted.

Verrain Crossing Feature	es Report	oort Crossir	ng Features	s - Report		×
🕒 Feature Types 🔹 🔑 Zo	oom To 📓 Report All 📓 In	View 🚞 Export 🖉 Draw	Selected Radius: 5			
Intersection Point	Elevation On Feature 1	Elevation On Feature 2	Elevation Difference	Feature Type 1	Feature Type 2	
2263336.142, -3123948.744	1411.643	Zoom To Report All In View	0.041	Breakline	Breakline	
<b>T</b> t	ools for fixing the Elevation Discrepancy	DeleteFeature1 DeleteFeature2 Insert a Point into bo Insert a Point into bo Insert point from Fea Automatically fix Fie	th Features at a defined Eleva th Features at an average Elev ture 1 into Feature 2 ture 2 into Feature 1 varians	ation vation		\$

	Elevation Discrepancy Tools
Tool:	Description:
Delete Feature 1	Feature 1 is removed from the Terrain Model. <b>NOTE:</b> The element that corresponds with Feature 1 is NOT deleted. Only removed from the Terrain.
Delete Feature 2	Feature 2 is removed from the Terrain Model.
Insert a Point into both Features at a defined Elevation	An elevation point is inserted into both Features. The elevation of the point is specified by the User.
Insert a Point into both Features at an average Elevation	An elevation point is inserted into both Features. The elevation of the point is the average of "Elevation on Feature 1 and 2".
Insert point from Feature 1 into Feature 2	A point is inserted into Feature 2. The elevation of the point matches the "Elevation on Feature 1".
Insert point from Feature 2 into Feature 1	A point is inserted into Feature 1. The elevation of the point matches the "Elevation on Feature 2".
Automatically fix Elevations	The User is prompted to enter a "Maximum Elevation Difference". Then the average elevation at the Intersection Point is calculated. The average elevation is used if the resulting point does NOT exceed the "Maximum Elevation Difference" value in respect to "Elevation of Feature 1 and 2". If the "Maximum Elevation Difference" is exceeded, then the inserted point is adjusted to an elevation that is NOT exceeded.

# 21E.2 Report Conflicting Points tool

This tool analyzes a Terrain Model for two or more Points placed at in the same horizontal position, but at different elevations.

For example, a Terrain Model used to create the surface of an Approach requires a closed Boundary element to be created. When creating the Profile of the Boundary element, the start point of the Profile should be placed at the same elevation as the end point.

However, if the start and end point are errantly placed at differing elevations, the conflicting elevations will be located and listed by the *Report Conflicting Points* tool. Also, the differing elevation points can be automatically reconciled by this tool.



1	From the Ribbon, select the <i>Report Conflicting Points</i> tool: [ <i>OpenRoads Modeling</i> $\rightarrow$ <i>Terrain</i> $\rightarrow$ <i>Analysis</i> $\rightarrow$ <i>Reporting</i> ].
2	Prompt: Select Terrain Model element – Select (left-click) on the Terrain Model to analyze.
	<i>Prompt: Apply Elevation Tolerance</i> – If NO is selected, then the resulting report will list All points that are placed in the same horizontal position. Even points are placed at same elevation (Elevation Difference = 0.0000) are listed in the report.
3	If YES is selected, then an <b>Elevation Tolerance</b> must be specified in step 4. The Elevation Tolerance is used to filter out same position points with an elevation difference smaller the specified tolerance.
	<b>TIP:</b> To analyze for same position points with conflicting elevation values, set the Elevation Tolerance to a very small value (i.e., 0.0001). Same position points placed at equal elevations will NOT be listed.
4	<i>Prompt: Set Elevation Tolerance</i> – Key-in the desired Elevation Tolerance for the analysis.

After step 4, the *Report Conflicting Points* report is created and all conflicting points in the Terrain Model are listed. As shown in the report below, there is an Elevation Difference of 0.152 feet at the Start/End Point of the Boundary element.



By Right-Clicking on a Point, the elevation discrepancy can be automatically fixed.

Terrain Conflicting Points Report	ort Cor oints R	nflicti Report	ng t			X		
🔑 Zoom To 횔 Report All 🧕 In View 🌔	🔁 Export 🛛 🖉 🛙	Draw Selected	Radius: 5					
Point Location	Elevation Differe	ence	Elevation at Point	Elevation on Terrain Model				
2467812.253, 2565957.305 * Terrain Point 2467812.253, 2565957.305	-0.152		1761.500	1761.586				
	13	Zoom To Report All In View						
Tools for	fixing	Delete Point						
Discrep	ancy	Set Point to	Elevation	_		>		

	Elevation Discrepancy Tools
Tool:	Description:
Delete Point	The selected Point is deleted. If the "Terrain Model" Point is deleted, then the elevation of the other point is used at the conflicting point location.
Set Point to Average Elevation	The elevations of the two conflicting points are averaged and the Terrain Model is automatically adjusted at the point location.
Set Point to Elevation	The selected Point is set to an elevation specified by the User.

#### **21F – AQUAPLANING TOOL**

The *Aquaplaning* tool analyzes the Finished Ground Terrain Model to create a report that measures film depth along the length of the road for a specified rainfall intensity.

**NOTE:** The FLH WorkSpace does NOT support Feature Definitions for use of this tool. This tool is NOT used in FLH projects.



**TIP:** Analyzing the Corridor or Finished Ground Terrain Model with Thematic Displays can be used to identify flat areas that may result in ponding or aquaplanning. For more information on Thematic Displays, see <u>21H</u> – Use Thematic Display Styles to Analyze Slopes.

#### **21G - SIGHT VISIBILITY TOOL**

The *Sight Visibility* tool generates sight lines and a report that analyzes the Stopping Sight Distance (SSD) or Passing Sight Distance (PSD) at station intervals along the mainline alignment.



In practice, this tool has two main usages:

- Determine areas with inadequate Stopping Sight Distance (SSD). For example, if an object was placed on the roadway, this tool analyzes if a vehicle has adequate Stopping Sight Distance to come to a stop before reaching the object.
- Analyze Passing Sight Distance (PSD) to determine passing zones. Once passing zones are determined, appropriate pavement markings can be drawn in for the permeant traffic control plan. For example, for two lane highways, this tool can be used to determine placement of broken yellow centerline markings that designate passing zones.

# 21G.1 Capabilities and Limitations of the Sight Visibility tool

At every station interval, this tool draws a 3-dimensional sight line from the eye location of the motorist to the object location, which is placed further down the mainline alignment. The distance from the eye location to the object is set by the SSD or PSD distance required for the motorist operating speed. The SSD or PSD distance is measured along the Alignment and represents the path of the vehicle.



In operation of this tool, the Proposed Finished Grade Terrain Model or a Corridor is selected. Sight Line failure is determined if the Finished Grade Terrain Model or Corridor obstructs the sight line from the eye location to the object. Acceptable sight lines are shown in green. Failed sight lines are shown in red.

As shown below, the sight line is shown in red (failure) because the proposed crest vertical curve interrupts the sightline between the eye and object.



**Sight Lines that extend past the Finished Grade Terrain Model or Corridor:** Optionally, this tool allows the Existing Ground Terrain Model to be selected to further analyze sight lines that extend past the selected Finished Grade Terrain Model/Corridor. In areas where the Existing Ground Terrain Model and Finished Grade Terrain Model/Corridor overlap, the Existing Ground Terrain Model is ignored.

**Limitation – Accounting for Other Vertical Obstructions (i.e., trees and buildings):** As mentioned above, this tool analyzes Terrain Models and/or Corridors for sight line obstructions due to grade changes. Trees, buildings, and other vertical obstructions are NOT analyzed because they are NOT a part of the Existing Ground Terrain Model.

Accounting for vertical obstructions can be done manually by examining the resulting sight lines from the 2D Design Model  $\Omega$  (plan view). **BEST PRACTICE:** After using this tool, scroll down the alignment and search for sight lines that extend past vertical obstructions (i.e., trees, buildings, clearing limits) or the right-of-way.

**TIP:** Turn on the *Background Map* aerial to assist in identifying vertical obstructions. See <mark>3D – Setup a New ORD File</mark>.



For example, in the graphic above, all sight-lines are deemed acceptable by the *Sight Visibility* tool because the Terrain Models/Corridor grade changes do NOT obstruct the sight-line. However, there is an area that would be obstructed by the surveyed Tree Line.

**TIP:** When scrolling down the alignment, isolate Levels that correspond with vertical obstructions, such as the tree line (E\_VEG\_Tree\_Line), buildings (E\_PLM\_BLDG\_Building), and clearing limits (P\_RDW\_Clearing\_Limts). Also, it is commonly undesirable to have sight lines extend past the existing or proposed right-of-way and property lines (E\_RW\_Right\_of\_Way\_Lines, P\_RW\_Right\_of\_Way).

**TIP:** In step 29 of the <u>21G.2 Sight Visibility – Workflow</u>, the start station for analysis is specified. Before accepting the start station, a sight line is dynamically drawn. Move the dynamic sight line down the length of the alignment to quickly identify locations that are obstructed by surveyed or proposed linework.

Vertical obstructions can be automatically analyzed by creating a 3D model of the obstruction and adding it to the Existing Ground Terrain Model. However, modeling each obstruction area can be very time consuming and will slightly alter the triangulation of the Existing Ground Terrain Model when added.



In summation, the process for modeling an obstruction area is as follows:

**NOTE:** For this process, a new ORD File should be created. The Survey ORD File must be *merged* (imported) into the new ORD File to make modifications to the Existing Ground Terrain Model. Specifically, the Survey ORD File must be *merged* into the *3D Design Model* to import the Existing Ground Terrain Model.

1	Create a new ORD File using a 2D Seed File.
2	Reference in the Survey ORD File and activate the Existing Ground Terrain Model.
3	Enter the <i>3D Design Model</i> of the new ORD File. Open the References manager. Select (highlight) the Survey ORD File and use the <i>Merge Into Master</i> tool. See <b>1</b> <i>E7.a Merge into Master tool (Import Reference into Current ORD File)</i> . <b>WARNING:</b> If the <i>Merge Into Master</i> tool is used when the <i>2D Design Model</i> S is <i>active</i> , then the Terrain Model is converted to a Cell element.
4	Return to the 2D Design Model $\mathfrak{D}$ of the new ORD File and activate the merged (imported) Existing Ground Terrain Model.
5	Create Closed Shape elements (MicroStation Elements) that represent the Obstruction Area. <b>TIP:</b> Combine Linework that represents obstruction areas using the <i>Create Complex Shape</i> tool. <b>TIP:</b> Turn on the <i>Background Map</i> aerial to trace obstruction areas. <b>TIP:</b> Use the <i>Copy</i> tool with referenced Linework to import the desired lines into the new ORD.
	File.

Open the *Profile Model*  $\boxplus$  for an Obstruction Area element.

Using the *Copy* tool, copy the profile for the Existing Ground Profile and place it in the same location. *Activate* the copied Profile.

**WARNING:** Do NOT directly activate the Existing Ground Profile. Activate the copy. If the Existing Ground Profile is directly activated, then the Obstruction Area element will be rejected when adding it to the Existing Ground Terrain Model.

Return to the 2D Design Model  $\Omega$ .

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Using the *Move Parallel* tool, create an offset copy of the Obstruction Area element. Place the Offset element 0.5 feet within the Obstruction Area element.

Open the *Profile Model*  $\boxplus$  for the offset copy.

Using the *Copy* tool, copy the Existing Ground Profile and place it directly above the original location using AccuDraw. Place the copy 15-20 feet above original location. *Activate* the copied Profile.



Enter the 3D Design Model 둷.

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**NOTE:** After *activating* the Profiles for both the Obstruction Area element and Offset element, corresponding *3D Linear Elements* are shown in the *3D Design Model*

Add the 3D Linear Elements to the Existing Ground Terrain Model using the Add Features tool.

**IMPORTANT:** Add the Obstruction Area element as a Break Line.

**IMPORTANT:** Add the Offset element as a Break Void.

**NOTE:** When using the *Add Features* tool, the elements to be added must be selected from the *3D Design Model*



**Limitation – Accounting for Grade in SSD Calculations:** A variable in the Stopping Sight Distance (SSD) formula is the current grade (G) that the vehicle is traveling on.

Greenbook Equation (3-3):

$$d_B = \frac{V^2}{30[\frac{a}{32.2} \pm \text{G}]}$$

Where:

 $d_B$  = Breaking Distance on grade (ft)

V = Design speed (mph)

a = deceleration (ft/s<sup>2</sup>)

G = Current Grade (%)

Unfortunately, the ORD software suffers from a known bug, that prevents the Instantaneous Grade and Average Grade information to be collected, which means the calculated Stopping Sight Distance does NOT account for Average Grade.

3	Sight Visibil	ity Results -	Section: PSI	D			Sigh Res	t Vis ults	sibility Table	]				×
$\checkmark$	Achieved	Relaxed	🗸 Not Achi	eved 🗌 Sh	ow Selected	1								•
	Eye Position	Object Position	Eye Level	Actual Level	Object Level	Design Speed	Instantaneous Grade	Average Grade	Sicht Disance Required	Relaxed	Sight Distance Achieved	Sight Distance Along Sight Line Achieved	Sight Line Status	^
►	11+38.51	16+88.51	1792.7832	1786.2484	1786.2484	35.0000	0.00%	0.00%	50.0000	550.0000	550.0000	544.3354	Achieved	
	11+88.51	17+38.51	1786.1665	1786.1776	1786.7304	35.0000	0.00%	0.00%	50.0000	550.0000	10.2574	10.6871	Not Achieved	d de la companya de l
	12+38.51	17+88.51	1789.1291	1787.5006	1787.5006	35.0000	0.00%	0.00%	50.0000	550.0000	550.0000	548.8141	Achieved	
	12+88.51 13+38.51 13+88.51 14+38.51 14+88.51	18+38.51 18+88.51 19+38.51 19+88.51 20+38.51	1787.7366 1786.7850 1786.2892 1786.1221 1786.0821	1788.5508 1789.9137 1791.5665 1793.3229 1795.0784	1788.5508 1789.9137 1791.5665 1793.3229 1795.0784	35.0000 35.0000 35.0000 35.0000 35.0000	0.00% 0.00% 0.00% 0.00%	0.00% 0.00% 0.00% 0.00%	5 5 5 5 5	ntaneous columns	NOTICE: Itaneous Grade and Average columns are shown at 0.00%			
	15+38.51	20+88.51	1786.0680	1792.4041	1796.8343	35.0000	0.00%	0.00%	50.0000	550.0000	321.0150	319.8967	Not Achieved	d
	15+88.51	21+38.51	1786.0539	1792.3204	1798.5927	35.0000	0.00%	0.00%	50.0000	550.0000	271.3772	270.9432	Not Achieved	d 👘
	16+38.51	21+88.51	1786.0499	1791.9441	1800.3499	35.0000	0.00%	0.00%	50.0000	550.0000	221.6572	222.3737	Not Achieved	d
	16+88.51	22+38.51	1786.2484	1791.3981	1802.1044	35.0000	0.00%	0.00%	50.0000	550.0000	171.6931	173.9725	Not Achieved	d
	17+38.51	22+88.51	1786.7304	1790.7478	1803.7737	35.0000	0.00%	0.00%	50.0000	550.0000	121.3102	125.1628	Not Achieved	d
	17+88.51	23+38.51	1787.5006	1790.5489	1804.4880	35.0000	0.00%	0.00%	50.0000	550.0000	90.1789	94.4001	Not Achieved	d
	18+38.51	23+88.51	1788.5508	1791.3753	1803.9721	35.0000	0.00%	0.00%	50.0000	550.0000	91.5561	95.6569	Not Achieved	d 🗸 🗸

As a workaround, FLH has a Microsoft Excel spread sheet template that calculate Average Grade based on the **Eye Level** and **Object Level** elevations. The values generated in the **Sight Visibility Results Table** are copied into FLH spread sheets to automatically calculate SSD values that account for grade. Exporting the Sight Visibility Results table into the FLH spread sheet template is discussed in <u>21G.3 Import Results</u> into Microsoft Excel Template.

**TIP:** Another workaround for addressing the average grade bug is to locate steepest grade on the project from the Alignment Profile. Use Table 3-2 from the AASHTO Greenbook to determine the SSD distance for the steepest grade. In step 10 of the *21G.2 Sight Visibility - Workflow*, a custom Distance (SSD) value can be specified. Enter the SSD distance for the steepest grade during this step. The resulting analysis will be more conservative because the worst-case situation is analyzed.

**Limitation – Maximum Sight Distance is NOT Calculated:** Knowing the Maximum Sight Distance that a motorist can see is beneficial in areas of marginal SSD or PSD. This tool does NOT provide additional analysis or extend a sight line after SSD or PSD is achieved.

For example, if the SSD is 200 feet (speed = 30 mph), analysis is ceased when determined that 200 feet of Sight Distance is achievable. In this case, the motorist has a Maximum Sight Distance of 220 feet (As shown in the results table below), which is marginal compared to the SSD of 200 feet. This marginal area may be of interest to the designer.



As a workaround, the operating speed or SSD (Distance) variable can be increased when using the *Sight Visibility* tool. In the example shown above, failure is invoked by increasing the speed from 30 mph to 35 mph, which changes the target SSD value from 200 feet to 250 feet.

In the Sight Visibility Results Table, failed sight lines (shown with red rows) can be analyzed in the **Sight Distance Achieved** column. The value shown in this column is the Maximum Sight Distance at the station.

Sight Visibilit ☑ Achieved ☑	Re Sp S Selected	esu Dee SD	lts ed = = 2	Tal 35 250	ole 5 Ml 9 Fe	for PH et	] _	Sight [	<b>)istanc</b> colur	e / nn	Achieved			
Eye Position	Object Position	Eye Level	Actual Level	Object Level	Design Speed	Instantaneo Grade	Average Grade	Sight Distance Required	Sight Distance Relaxed	Sight Distance Achieved	Sight Distance Along Sight Line Achieved	Sight Line Status	^	
17+50.00	20+00.00	1785.8792	1800.0238	1800.0238	35.0000	0.00%	0.00%	250.0000	250.0000	250.0000	248.0853	Achieved		
18+00.00	20+50.00	1787.7387	1803.8929	1803.8929	35.0000	0.00%	0.00%	250.0000	250.0000	250.0000	247.8725	Achieved		
20+50.00	21+	OTIC		Ctati	on 2		) +b.	000	250.0000	250.0000	248.7242	Achieved		
20+00.00	20+			้วเล่น	on 2	2+50	, une	e <sub>000</sub>	250.0000	250.0000	247.8725	Achieved		
20+50.00	<sub>20+</sub> Ma	axim	um S	ight	Line	e Dist	tanc	е 🚾	250.0000	250.0000	248.7242	Achieved		
21+00.00	21+		is 2	220 Feet. 000 250.000				250.0000	250 0000	247.8725	Achieved			
21+50.00	20+50.00	1785.8792	1800.0238	1807.1974	35.0000	0.00%	0.00%	250.0000	250.0000	250. 000	248.7242	Achieved		
22+00.00	21+00.00	1787.7387	1803.8929	1800.0238	35.0000	0.00%	0.00%	250.0000	250.0000	250. 00	248.7242	Achieved		
22+50.00	22+80.00	1810.1150	1807.5704	1807.5704	35.0000	0.00%	0.00%	250.0000	250.0000	220.0000	129.2096	Not Achieved		
23+00.00	23+30.00	1810.6387	1804.4761	1804.4761	35.0000	0.00%	0.00%	250.0000	250.0000	240.0000	129.2096	Not Achieved		
23+50.00	25+00.00	1809.7685	1790.2069	1790.2069	35.0000	0.00%	0.00%	250.0000	250.0000	250.0000	248.7442	Achieved		
24+00.00	25+50.00	1807.5044	1785.9914	1785.9914	35.0000	0.00%	0.00%	250.0000	250.0000	250.0000	249.6861	Achieved		
23+50.00	26+00.00	1803 8535	1781 7759	1781 7759	35,0000	0.00%	0.00%	250 0000	250 0000	250.0000	249 8995	Achieved	$\sim$	

**BEST PRACTICE:** When using the *Sight Visibility* tool, set the Speed to 5-10 mph greater than the actual operating speed of the road. For failed sight-lines, compare the **Sight Distance Achieved** with the actual SSD of the road. This practice allows areas of marginal SSD to be identified.

**Limitation – Only 1 Direction of Traffic is Analyzed per Use of the Tool:** This tool can analyze sight lines either forwards or backwards along the alignment. However, it CANNOT analyze both directions at the same time.

To analyze sight lines **forwards** along the alignment, the start station must be less than the end station.

To analyze sight lines **backwards** along the alignment, set the start station to a value grater than the end station.

🔏 Sight Visibility		- 🗆 X	
Parameters			
Lock To Start		To run the to	ol <b>backwards</b> along
Start	12+50	the	Alignment:
Lock To End			
Stop	8+00	Set the Start	Station to a greater
Settings File Name	C:\ProgramData\Bentley\OpenRoads Designer CE 10.10\Config	value than	the End Station
Method	Table	value than	the Life Station
Table Name	AASHTO 2011 Stopping on Level Roadways	~	
Speed	35	~	
Required Distance	250.0000		
Relaxed Distance	250.0000		
Eye Position		*	
Interval	50.0000		
Offset	-4.0000		
Height	3.5000		
Object Position		*	
Move Target To Achieve Visibility			
Interval	10.0000		
Offset	0.0000		
Height	2.0000		
Feature		*	
Feature Definition	Stopping Sight Distance	~	
Name	SSD		

**TIP:** When analyzing **backwards** along the alignment, set the start station to a round station (i.e., 12+50). In the resulting report, the station intervals will be set to round values (i.e., 12+50, 12+00, 11+50, etc...).

**WARNING:** If the start station is set to an irregular station (i.e., 12+56.23), then then resulting report will list station intervals relative to the start station (i.e., 12+56.26, 12+06.56, 11+56.26, etc...).

# 21G.2 Sight Visibility – Workflow

In this workflow, the *Sight Visibility* tool is used to generate sight lines and a results report.

When using this tool either the Alignment or Corridor can be selected (which is shown in step 26). If the Alignment is selected, then a **Design Surface** (i.e., the Proposed Finished Grade Terrain Model) must also be selected. The Design Surface is used to calculate the Eye Level and Object Level and analyze for obstructions due to grade change. Creating a Finished Grade Terrain Model from a Corridor is shown in *22A.1 Create Terrain Model from Design Meshes tool*.

**Selecting the Corridor vs Alignment/Design Surface:** If the Corridor is selected, then only the top surface of the Corridor is analyzed for sight line obstructions. If an Alignment/Design Surface is selected, then a Design Surface can be created using a combination of Corridors, Linear Templates, and Surface Templates. All Corridors, Linear Templates, and Surface Templates included in the Design Surface are analyzed for sight line obstructions.

**NOTE:** As stated above, either the Corridor or the Alignment/Design Surface can be selected. Regardless of the selection, the Existing Ground Terrain Model can also be selected. In areas beyond the Corridor or Alignment/Design Surface, the Existing Ground Terrain Model is analyzed for sight line obstructions.

	Create a new ORD File using a 2D Seed File. See 3B – Create a New ORD File.
	<b>TIP:</b> Set the Coordinate System for the new ORD File. The Coordinate System must be set to use the <i>Background Map</i> tool.
2	In the new ORD File, reference in the Survey ORD File, Alignment ORD File, and Corridor ORD File, and any other pertinent Design ORD Files.
3	Activate the Existing Ground Terrain Model.
4	OPTIONAL: If an Alignment/Design Surface is to be selected in step 26, then create a Finished Grade Terrain Model use the <i>Create Terrain Model From Design Meshes</i> tool. Selecting the Alignment/Design Surface is useful when a Design Surface has been created that is comprised of multiple Corridors, Linear Templates, and/or Surface Templates. All features used to create the Design Surface is analyzed.

OpenRoads N	lodeling	• 🐼 • 💼 🖡	- 14 R	5 🐟 🔻 🤌	📌 🚔 🖡	. 🥪 🐔	Ŧ					
File Home	Terrain	Geometry	Site	Corridors	Model [	Detailing	Drawing Pro	duction	Drawing	Annotate	Utiliti	
Element Selection	<b>○</b> □ +	A From File From Graphica A From Elements	l Filter 🔻	Additional Methods •	Topo Import •	Active	Add Feature Add Feature Remove Feat Change Feat	s tures ure Type	ba Edit Mode a Edit Comp ↓ Boundary	l Ilex Model Options + Ti	ransform	
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View 2, Design	SurvFt-3D		1,0	Image: Second state	e Terrain Mo e From Poin e Clipped Te e Complex 1 e Delta e Corridor A e Terrain Mo	odel From t Cloud errain Mo Ferrain M Iternate t odel from	Ascii File del odel Design Meshes					
4 Use the Create Terrain Mode from Design Meshes tool to cre a Finished Grade Terrain Mod Finished Grade Terrain												



This tool requires the User to follow *Prompts* (shown around the mouse cursor) and configure the *Dialogue Box* for correct operation.

**Dialogue Box Configuration:** Steps 6-11 explain how to configure the **Parameters** options in the *Dialogue Box*.

	Sight Visibility	Sight Visibility Dialogue Box – D ×	
	Parameters	^	
	Lock To Start		
	Start	17+51.68	
	Lock To End		
File	Stop	18+25.71	
	Settings File Name	C:\ProgramData\Bentley\OpenRoads Designht Visibility\Sight Visibility	
	Method	Table	
	Table Name	AASHTO 2011 Stopping on Level Roadways	
	Speed	15	
	Required Distance	80.0000	
	Relaxed Distance	80.0000 Required Distance	e 10
	Eye Position	Relaxed Distance	e 11
	Intonyal	50,0000	
	mervar	50.0000	
	Offset	0.0000	
	Offset Height	0.0000 3.5000	
	Offset Height Object Position	0.0000 0.0000 3.5000	
	Offset Height Object Position Move Target To Achieve Visibility	0.0000       3.5000	
	Offset Height Object Position Move Target To Achieve Visibility Interval	0.0000 0.0000 3.5000 10.0000	
	Offset Height Object Position Move Target To Achieve Visibility Interval Offset	0.0000       3.5000       10.0000       0.0000	
	Offset Height Object Position Move Target To Achieve Visibility Interval Offset Height	0.0000         3.5000         10.0000         0.0000         2.0000	
	Offset Height Object Position Move Target To Achieve Visibility Interval Offset Height Feature	0.0000         3.5000         10.0000         0.0000         2.0000	
	Offset Height Object Position Move Target To Achieve Visibility Interval Offset Height Feature Feature Definition	50.0000         0.0000         3.5000         10.0000         0.0000         2.0000         2.0000         Stopping Sight Distance	

6	<b>Settings File Name:</b> The Settings File is a configuration file that contains AASHTO SSD and PSD tables. Press the button to select the Settings File. This file is located in the FLH WorkSpace in following location:
	\OpenRoads Designer CE 10.10\Configuration\Organization-Civil\FLH_Stds- WS10.10.21.00V\Sight Visibility
7	Method: To use the Settings File (selected in step 6), then select the Table method.
	<b>NOTE:</b> All other Method options require a <i>Speed Table</i> to be set for the Alignment.
	Table Name: The Table Name determines whether Stopping Sight Distance (SSD) orPassing Sight Distance (PSD) is analyzed.
8	<ul> <li>AASHTO 2018 Stopping on Level Roadways – Uses Greenbook Table 3-1 to determine</li> <li>Stopping Sight Distance (SSD)</li> <li>AASHTO 2018 Passing – Uses Greenbook Table 3-5 to determine Passing Sight Distance (PSD).</li> </ul>
	Speed: Select the design speed (in MPH).
9	<b>BEST PRACTICE:</b> Set the speed 5-10 MPH above the project design speed, which allows for analyzation of SSD/PSD in marginal areas. For more information, see <b>Limitation – Maximum Sight Distance is NOT Calculated</b> in 21G.1 Capabilities and limitation of the Sight Visibility tool.
10	<b>Required Distance:</b> The Required Distance sets the SSD or PSD for sight line analysis. By default, this value is automatically set by the <b>Table Name</b> (step 8) and <b>Speed</b> (step 9). Changing this value results in an overridden SSD or PSD.
11	<b>Relaxed Distance:</b> The Relaxed Distance parameter is NOT used in AASHTO SSD and PSD analysis. However, ensure this value matches the Required Distance (Step 10).

Steps 12-17 explain how to configure the **Eye Position** and **Object Position** options in the *Dialogue Box:* 





18



**NOTE:** The Feature Definition does NOT affect the analysis or calculations made by the software. The Feature Definition is simply used to organize different runs of the *Sight Visibility* tool in the Explorer **a**.

19 Assign the *Sight Visibility* run a descriptive **Name**. For example: "SSD Eastbound 40 MPH".

	Sight Visibility	Sight Visibility Dialogue Box - • ×
	Parameters	^
	Lock To Start	
	✓ Start	10+00.00
	Lock To End	
	Stop	102+76.21
	Settings File Name	C:\ProgramData\Bentley\OpenRoads Designe Visibility\Sight Visibility
	Method	Table
	Table Name	AASHTO 2011 Stopping on Level Roadways
	Speed	15
	Required Distance	100.0000
	Relaxed Distance	80.0000
	Eye Position	*
	Interval	50.0000
	Offset	9.0000
	Height	3.5000
	Object Position	*
	Move Target To Achieve Visibility	$\checkmark$
18	Interval	10.0000
	Offset	0.0000
Feature Definition	Height	2.0000
19	Feature	^
	Feature Definition	Stopping Sight Distance
Name	Name	SSD Eastbound 40 MPH

The remainder of the steps in this procedure follow the *Floating Prompts*. **NOTE:** Steps 20-25 correspond with steps 6-11, which where set in the *Dialogue Box*. The parameters and values set in the *Dialogue Box* will display in the *Floating Prompt* box.

20	<i>Prompt: Select Settings File</i> – The <b>Setting File</b> was set in step 6 through the <i>Dialogue Box</i> . Confirm the correct settings file is shown and left-click anywhere in the <i>View</i> window to advance to the next step.
21	<i>Prompt: Method</i> – The <b>Method</b> was set in step 7 through the <i>Dialogue Box</i> . Left-Click anywhere in the <i>View</i> window to advance to the next step.
22	<i>Prompt: Table Name</i> – The <b>Table Name</b> was set in step 8 through the <i>Dialogue Box</i> . Left-Click anywhere in the <i>View</i> window to advance to the next step.
23	<i>Prompt: Speed</i> – The <b>Speed</b> was set in step 9 through the <i>Dialogue Box</i> . Left-Click anywhere in the <i>View</i> window to advance to the next step.
24	<i>Prompt: Required Distance</i> – The <b>Required Distance</b> (SSD or PSD) was set in step 10 through the <i>Dialogue Box</i> . Left-Click anywhere in the <i>View</i> window to advance to the next step.
25	<i>Prompt: Relaxed Distance</i> – The <b>Relaxed Distance</b> was set in step 11 through the <i>Dialogue Box</i> . Left-Click anywhere in the <i>View</i> window to advance to the next step.



	<i>Prompt: Locate Corridor or Alignment</i> – Left-Click on either the Corridor Handle (tick) or the Alignment.
26	If the <b>Alignment</b> is selected, then a <b>Design Surface</b> must be selected in step 31. The Design Surface is analyzed for sight line obstructions.
	If the <b>Corridor</b> is selected, then the original Corridor Alignment is used for stationing and the top surface of the Corridor is analyzed for sight line obstructions. Step 31 is NOT shown when the Corridor is selected.
	<i>Prompt: Locate Eye Control Alignment – Reset for Main Alignment –</i> Optionally, a custom Alignment can be used to control the horizontal position of the Eye. If an Eye Control Alignment is used, then main Alignment is ONLY used for stationing purposes.
27	<b>TIP:</b> An Eye Control Alignment is NOT necessary if an <b>Eye Position Offset</b> is specified in Step 13.
	Right-Click (reset) to forgo an Eye Control Alignment and use the main Alignment to control the Eye Position.
28	Prompt: Locate Object Control Alignment – Reset for Main Alignment – Optionally, a custom Alignment can be used to control the horizontal position of the Object. However, the Object Control Alignment is NOT necessary if an <b>Object Position Offset</b> is specified in Step 16.
	Right-Click (reset) to forgo an Object Control Alignment and use the main Alignment to control the Object Position.



	<i>Prompt: Start Station <alt> Lock to Start –</alt></i> Select a Start Station with the mouse-cursor or enter a value into the <i>Dialogue Box</i> .
29	<b>TIP:</b> If the start station is set to an irregular station (i.e., 12+56.23), then then resulting report will list station intervals relative to the start station (i.e., 12+56.26, 12+06.56, 11+56.26, etc).
	<b>TIP:</b> Hover the mouse cursor along the length of the Alignment to show a dynamic sight line. Look for area where the dynamic sight line crosses vertical obstructions linework (i.e., tree line, buildings, right-of-way lines).
30	<i>Prompt: End Station <alt> Lock to End –</alt></i> Select an End Station with the mouse-cursor or enter a value into the <i>Dialogue Box</i> .
31	Prompt: Locate Design Surface – Select the Finished Grade Terrain Model.
	<b>NOTE:</b> This step is ONLY shown if the Alignment was selected in step 26.
32	<i>Prompt: Locate Existing Surface – Reset to Skip –</i> Select the Existing Ground Terrain Model. The Existing Ground Terrain Model is analyzed for sight line obstructions in areas that extend past the Finished Grade Terrain Model/Corridor.



*Prompt: Data Point to Accept Design* – Left-Click in the *View* window to place the sight line graphics and view the results table.

33

**TIP:** There are two methods for deleting a previously-created run of the Sight Visibility tool:

- Select the sight line elements from the **3D Design Model** <sup>€</sup> and delete it. **NOTE:** Sight-lines CANNOT be deleted by selecting the sight lines in the 2D Design Model **2**.
- Locate the Sight Visibility run in the Explorer <a></a>. Previously-created Sight Visibility runs are located under the OpenRoads Model drop-down and in the Sight Visibility Sections drop-down.

**TIP:** Retrieve a Sight Visibility Results Table for a previously-created run from the Explorer **C**: Right-Click on the run and select the *Sight Visibility Results* option.



#### TIP: Export the Sight Visibility Results Table to Microsoft Excel:

<b>S</b>	Sight Visibil Achieved [·	lity Results - S ☑ Relaxed ☑	ection: SSD	Eastbound 3 ed Shov	30MPH v Selected	/	S	elect tl bu	he <b>Rep</b> Itton	oort 🥖	]	-		< •
	Eye Position	Object Position	Eye Level	Actual Level	Object Level	Design Speed	Instantaneous Grade	Average Grade	Sight Distance Required	Sight Distance Relaxed	Sight Distance Achieved	Sight Distance Along Sight Line Achieved	Sight Line Status	^
•	10+00.00	10+10.00	1788.9378	1792.3334	1792.3334	15.0000	0.00%	0.00%	80.0000	80.0000	10.0000	10.0000	Not Achi	
	10+50.00	11+30.00	1794.1204	1791.4846	1791.4846	15.0000	0.00%	0.00%	80.0000	80.000	80.000	80.0000	Achieved	
	11+00.00	11+60.00	1793.6950	1790.5580	1790.5580	15.0000	0.00%	0.00%	80.0000	80.0000	60.0000	59.9953	Not Achi	
	11+50.00	11+60.00	1792.4195	1790.5580	1790.5580	15.0000	0.00%	0.00%	80.0000	80.0000	10.0000	9.9998	Not Achi	
	12+00.00	12+80.00	1790.5022	1786.4427	1786.4427	15.0000	0.00%	0.00%	80.0000	80.000	80.000	79.9093	Achieved	
	12+50.00	13+30.00	1788.7673	1785.4132	1785.4132	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	79.9093	Achieved	
	13+00.00	13+80.00	1787.4736	1784.8478	1784.8478	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	79.9239	Achieved	
	13+50.00	14+30.00	1786.6212	1784.6437	1784.6437	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	79.9979	Achieved	
	14+00.00	14+80.00	1786.2099	1784.5845	1784.5845	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	80.0000	Achieved	
	14+50.00	15+30.00	1786.0930	1784.5704	1784.5704	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	80.0000	Achieved	
	15+00.00	15+80.00	1786.0789	1784.5563	1784.5563	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	80.0000	Achieved	
	15+50.00	16+30.00	1786.0648	1784.5423	1784.5423	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	80.0000	Achieved	
	16+00.00	16+80.00	1786.0507	1784.7016	1784.7016	15.0000	0.00%	0.00%	80.0000	80.0000	80.0000	80.0000	Achieved	
	16+50.00	17+30.00	1786 0602	1785 1359	1785 1359	15,0000	0.00%	0.00%	80,0000	80.0000	80,0000	80,0000	Achieved	<b>N</b>



As shown in the graphic report above, the Average Grade and Instant Grade columns are zeroed out. To account for grade in the SSD/PSD calculations, the results table must be imported into the FLH spread sheet template, which is shown the next section.

# 21G.3 Import Results into the Microsoft Excel Template

The resulting tables from the SSD or PSD analysis must be copied into FLH spreadsheet template to account for grade in the calculations and create a report. The FLH SSD and PSD spread sheet templates are located at:

https://highways.dot.gov/federal-lands/design/forms/sight-distance

1

2

3

**NOTE:** Generation of the Microsoft Excel results table from ORD is shown on the previous page. Both the ORD results and FLH template spread sheets must be opened for this procedure.



In the Microsoft Excel results table, select all cells by pushing the Triangle button located in the upper-left corner. Right-Click and select **Copy**.

In the FLH spread sheet template, select either the "Alg Upstation" or "Alg Downstation" tab. The selected tab depends on which direction along the alignment the Microsoft Excel Results table was generated from.

Select the Triangle button located in the upper-left corner. Right-Click and select **Paste**.



# Repeat Steps 1-3 for the opposing direction along the alignment. Ensure that results generated from ORD are copied into both the "Alg Upstation" and "Alg Downstation" tabs.

4

5

In the FLH spread sheet template, select either the "Upstation Analyzed" or "Downstation Analyzed" tab

Expand the **Design Speed** drop-down located in cell E1. Select the appropriate design speed.

Repeat steps 4-5 for the opposing direction along the alignment. Ensure the Design Speed has been selected in both the "Upstation Analyzed" and Downstation Analyzed" tabs.

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7	402+75	30	160	160	160	200	No	3532.627	-2.09	200	No	
8	402+65	30	200	200	200	200	Yes	3532.622	-2.09	200	Yes	
9	402+55	30	200	200	200	200	Yes	3532.698	-2.03	200	Yes	
10	402+45	30	200	200	200	200	Yes	3532.885	-1.87	200	Yes	
11	402+35	30	200	200	200	200	Yes	3533.135	-1.66	200	Yes	
12	402+25	30	200	200	200	200	Yes	3533.4	-1.43	200	Yes	
13	402+15	30	200	200	200	200	Yes	3533.664	-1.20	200	Yes	
14	402+05	30	200	200	200	200	Yes	3533.93	-0.97	200	Yes	
15	401+95	30	200	200	200	200	Yes	3534.21	-0.73	200	Yes	
16	401+85	30	200 J	200	200	200	Yes	3534.499	-0.48	200	Yes	
17	401+75	30	200			م ماط بد ا		4.796	-0.24	200	Yes	
18	401+65	30	200	5	elect elt	iner the	9	5.093	0.01	200	Yes	
19	401+55	30	200	"IInst	ation <b>A</b>	nalvze	d" or	35.36	0.24	200	Yes	
20	401+45	30	200					5.626	0.48	200	Yes	
21	401+35	30	200	Downs	tation	Analyz	<b>ed</b> " tal	5.891	0.71	200	Yes	
22	401+25	30	200	200	200	200	Yes	3536.143	0.93	200	Yes	
23	401+15	30	200	200	200	200	Yes	3536.366	1.14	200	Yes	
24	401+05	30	200	200	200	200	Yes	3536.545	1.33	200	Yes	
•	• ····	Cor Upstation	Cor Downstatio	n Upstation	Analyzed Do	wnstation Ana	lyzed Upst	ation Analyz	(+) : []	· · · · · · · · · · · · · · · · · · ·		
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After the design speed has been selected, select the "**Upstation Analyzed Filter**" and "**Downstation Analyzed Filter**" tabs to review the results. Results shown in the "Level Roadway Only (Tool Output)" table are generated directly from ORD. Results shown in the "Accounting for Grade" calculate the SSD with the effect of grade accounted for. These results use the ORD generated eye level and object level elevations to calculate an approximate average grade.

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3			(7.10.1					<b>D J</b>				
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5	Met	Station	SSD (LF)	SSD (LF)	Met	Station		SSD (LF)	SSD (L	F)		
6	Yes 💌	531+95 💌	200 💌	200 💌	#N/A 🖵	531+95	-	200 💌	#N/A	-		
28	No	526+45	5 495	200	No	526+45		5.495	200			
29		c	Select	either	the			10.285	200			
30								54.875	200			
31		"Upstatı	on An	alyze	ed Filt	er" or		48.701	200			
32	- "D	ownstat	tion A	nalvz	od Fil	tor" ta	h I	47.315	200			
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34	No	524+95	37.163	200	No	524+95		37.163	200			
35	No	524+70	18 5 3 2	267	No	524+70		18.832	200			
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#### **21H – USE THEMATIC DISPLAY STYLES TO ANALYZE SLOPES**

Using the "Thematic:Slope" Display Style, slopes along a Corridor, Linear Template, Terrain Model can be analyzed. The "Thematic:Slope" Display Style can be used to locate flat pavement areas where a drainage/ponding issue may form or to review slopes along a model to ensure ADA/ABA compliance.

The "Thematic:Slope" Display Style color-grades the surface of the Corridor, Linear Template, or Terrain Model. A legend is shown in the upper-right corner of the *View* window that identifies the approximate slope of each colored area.

**NOTE:** Thematic Display Styles are ONLY available in the *3D Design Model* **•**. This analysis must be performed from the *3D Design Model* **•**.



The "Thematic: Slope" Display Style must be edited in the Display Style Editor for effective use. By default, this Display Style uses degree units in the legend and color grading. The Display Style should be edited to show percent units, instead of the default degree units.

When editing the Display Style, a slope range should be specified. The default slope range (which is 0% to 100%) is too broad, which causes areas of shallow slope are displayed as completely flat. In the graphic above, the slope range is edited to ONLY show slopes from 0.00%-2.00%, which means slopes greater than 2.00% are NOT shown and color-graded.

Setting the range from 0.00%-2.00% is useful for locating areas where ponding or drainage may be an issue. The narrow slope range is necessary to depict small changes of slope in relatively flat areas. If the slope range was set from 0.00%-10.00%, then areas of slope between 0% and 1.9% are shown as completely flat (0.00%).

**BEST PRACTICE:** Set and adjust the slope range to isolate areas of interest. Engineering judgement may be required in setting the slope range for the particular analysis. A recommended slope range for identifying drainage and ponding issues is 0% - 2%. A recommended slope range for assessing ADA/ABA compliance is 2% - 10%.

#### Workflow for Setting and Editing the "Thematic:Slope" Display Style:



Transparent:Sky Sphere

Wireframe

5	In the Display Style Editor box, select (highlight) the "Thematic:Slope" style.					
6	Push the <b>Thematic Display</b> 📝 drop-down button.					
7	Set the <b>Display Mode</b> to <b>Percent</b> .					
	Set the Stepped Display to Accurate.					
8	<b>NOTE:</b> If the default option "Off (Smooth)" is used, then fine details in the grading are smoothed over and not depicted.					
	Set the <b>Slope Range</b> as appropriate for the analysis. Setting the Slope Range too broad is problematic because small changes in slope may NOT be depicted in the color grading.					
9	Slopes outside of the set range will NOT be shown as color-graded.					
	<b>BEST PRACTICE:</b> For analyzing flat areas for ponding or drainage issues, it is recommended that the Slope Range is set from 0.00% to 2.00%.					
	To analyze areas for ADA/ABA compliance, it is recommended that the slope range is set from 2% to 10%.					
	In all cases, engineering judgment is necessary for setting a slope range that isolates the areas of interest.					

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Display	/ Style		Hidden		Transparent Margins	Stepped Displ
		Usable for		-	_	to Accurate
	Thematic:HillShade		Views	Color Sche	eme: Blue - Red 🔻	
	Thematic:Slope		Clip Volumes			
	Transparent					
	Transparent:Modeling					
	Transparent:Shadows					
	Transparent:Sky Sphere		Slone Range	0.00%	2.00%	
<b>●</b> <sup>1</sup>	Wireframe 🗸 🗸		Slope Kange		• 2.00%	
<	>					0
						Set the
						Slone Range
						Crope Range